

FIN 395: Asset Pricing Theory

III. Arbitrage and the Stochastic Discount Factor

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- We explore the classic notion of no arbitrage and its implications.
- This is the most powerful preference-free concept in asset pricing.
- This will lead us to characterize objects generally useful in asset pricing
 - state prices, stochastic discount factor (SDF), martingale equivalent measures, . . .

- We can then relate these objects to utility maximization and Euler equations.
- Ask what can be recovered from asset prices and ways to specify SDF.
- We discuss the sharp contrast between complete and incomplete markets.

- **No Arbitrage and the Stochastic Discount Factor**
- Bounds on SDFs as a Diagnostic Tool
- Applications of SDF and Risk-neutral Measures

- Two dates $t = \{0, 1\}$.
- S states of the world at $t = 1$.
- Complete, symmetric information among market participants.
- Competitive markets: agents take prices as given.
- N securities, security i is a payoff vector $d_i = \begin{bmatrix} d_i^1 & d_i^2 & \dots & d_i^S \end{bmatrix}$.
- Payoff matrix D with $D_{is} = d_i^s$, $i \in \{1, \dots, N\}$ and $s \in \{1, \dots, S\}$.
- Portfolio: vector $\omega \in \mathbb{R}^N$.

Asset Span and Market Completeness

- Payoff of portfolio in state s is $\sum_i \omega_i D_{is}$ and payoff vector = $D'\omega$.
- The **asset span** associated with the payoff matrix is defined to be

$$\mathcal{M} = \left\{ \mathbf{z} \in \mathbb{R}^S : \mathbf{z} = D'\omega \text{ for some } \omega \in \mathbb{R}^N \right\}$$

- \mathcal{M} is a linear subspace of \mathbb{R}^S .
 - Complete markets implies $\mathcal{M} = \mathbb{R}^S$.
 - Markets are complete if and only if $\text{rank}(D) = S$
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- Canonical form of complete markets is set of **Arrow-Debreu** securities.
 - S securities, security s satisfies $d_s^s = 1$ and 0 otherwise.
 - Security i is **redundant** if $d_i = D'\omega$ with $\omega_i = 0$.
 - That is, asset is redundant if payoff can be replicated with other assets.

- An **arbitrage** is the possibility of positive payoffs at some date and state of the world, with no possibility of a negative cash flow at any date or state.
- We are interested in price systems that satisfy **no arbitrage**.
- That is, price systems such that no arbitrages exist.
- A weak requirement on asset prices.
- Also a **necessary condition for equilibrium** in financial markets.
- Preference-free in that it relies only on “more \succ less.”

- Let the vector of asset prices be $\mathbf{q} \in \mathbb{R}^N$.
- The cost of a portfolio ω is $\mathbf{q}' \cdot \omega = \sum_i q_i \omega_i$.
- An **arbitrage portfolio** $\omega \in \mathbb{R}^N$ is a portfolio such that

$$\mathbf{q}' \cdot \omega \leq 0 \text{ and } D' \cdot \omega > \mathbf{0},$$

or a portfolio such that

$$\mathbf{q}' \cdot \omega < 0 \text{ and } D' \cdot \omega \geq \mathbf{0},$$

Definition (State Prices)

Given a vector of asset prices \mathbf{q} , a vector of **state prices** ψ is such that

$$\mathbf{q} = D \cdot \psi.$$

- State prices can be interpreted as the marginal cost of a state-contingent payout.
- The key restriction is that it is a *linear* object.

Theorem (Fundamental Theorem of Finance)

Let D be a $N \times S$ matrix, and $\mathbf{q} \in \mathbb{R}^N$. There is no ω in \mathbb{R}^N satisfying

$$\mathbf{q}' \cdot \omega \leq 0 \text{ and } D' \cdot \omega \geq \mathbf{0},$$

with at least one strict inequality **iff** there exists $\psi \gg \mathbf{0} \in \mathbb{R}^S$ s.t. $\mathbf{q} = D \cdot \psi$.

In words: arbitrage holds **iff** there exists a strictly positive vector of state prices.

Proof. (IF).

Suppose there exists $\psi \gg \mathbf{0} \in \mathbb{R}^S$ such that $\mathbf{q} = D \cdot \psi$, and that there exists ω satisfying $\mathbf{q}' \cdot \omega \leq 0$ and $D' \cdot \omega \geq \mathbf{0}$. Then

$$0 \leq \psi' D' \cdot \omega = \mathbf{q}' \cdot \omega \leq 0.$$

This implies $\mathbf{q}' \cdot \omega = 0$. Since $\psi \gg \mathbf{0} \in \mathbb{R}^S$, then $D' \cdot \omega = 0$. □

Two Useful Mathematical Results (Referenced from Duffie)

Theorem (Separating Hyperplane Theorem)

Suppose that A and B are convex disjoint subsets of \mathbb{R}^N . There is some nonzero linear functional F such that $F(x) \leq F(y)$ for each x in A and y in B . Moreover, if x is in the interior of A or y is in the interior of B , then $F(x) < F(y)$. Furthermore, if A is closed and B is compact, then F can be chosen such that $F(x) < F(y)$ for all x in A and y in B .

Theorem (Linear Separation of Cones)

Suppose M and K are closed convex cones in \mathbb{R}^n that intersect precisely at zero. If K does not contain a linear subspace other than $\{0\}$, then there is a non-zero linear functional F such that $F(x) < F(y)$ for each x in M and each nonzero y in K .

Proof. (ONLY IF first part).

- Let $Q = \{(-\mathbf{q}' \cdot \omega, D' \cdot \omega) \mid \omega \in \mathbb{R}^N\}$, and $K = \mathbb{R}_+ \times \mathbb{R}_+^S$.
- For no arbitrage to hold, we must have $Q \cap K = \{0\}$. (Else there exists at least one portfolio such that $\mathbf{q}' \cdot \omega \leq 0$, $D' \cdot \omega \geq 0$ and one equality strict).
- This implies there exists an open cone $K' \supset K - \{0\}$ with $Q \cap K' = \emptyset$.

□

Fundamental Theorem of Finance

Proof. (ONLY IF second part).

- By the Separating Hyperplane Theorem, there exists $\phi \neq \mathbf{0}$ with $\phi' \cdot \mathbf{z} \leq \phi' \cdot \mathbf{x}$ for each $\mathbf{z} \in Q$ and $\mathbf{x} \in K$.
- Since Q is linear and K is a cone, $\phi' \cdot \mathbf{z} = 0$ for each $\mathbf{z} \in Q$, and $\phi' \cdot \mathbf{x} > 0$ for each $\mathbf{x} \neq \mathbf{0}$ and $\mathbf{x} \in K$ with $\phi' \gg \mathbf{0}$.
- Let us express $\phi = (\alpha, \tilde{\phi})$ with $\alpha \in \mathbb{R}$, and $\psi = \frac{\tilde{\phi}}{\alpha}$, and $\mathbf{z} = (-\mathbf{q}' \cdot \omega, D' \cdot \omega)$ Then

$$\phi' \cdot \mathbf{z} = 0 \implies \tilde{\phi}' \cdot (D' \cdot \omega) - \alpha \mathbf{q}' \cdot \omega = (D \cdot \psi)' \cdot \omega - \mathbf{q}' \cdot \omega = 0.$$

Since this must hold for each $\omega \in \mathbb{R}^N$, it follows

$$\mathbf{q} = D \cdot \psi.$$



Definition and Use of “No Arbitrage” Terminology

- We have considered two forms of pure arbitrage:
 1. a zero-cost portfolio that can generate positive profit with some probability.
 2. a positive payoff today that generates no losses tomorrow.
- This is the appropriate formal view of no-arbitrage.
- It is not necessarily the same as the colloquial use.
- For example, there is also “risk arbitrage”:
 - There is “mispricing” but arbitrageurs face risk in exploiting it for profit.
 - We will return to this issue when we discuss “limits of arbitrage”

Definition (Law of one Price)

Any two assets with the same cash flows must have the same price.

- LOOP is implied by no arbitrage. This follows from existence of state prices.
- Under no arbitrage, a portfolio ω with payoff schedule $D' \cdot \omega$ costs

$$\omega' \cdot \mathbb{E}^P [D \cdot \pi] = \omega' \cdot \mathbf{q},$$

- The weighted sum of prices of underlying securities that replicate payoffs.
- Frequent application: A risk-free portfolio must earn the risk-free rate.
- This observation be used to price derivatives.

Some Useful Properties of State Prices

- State prices ψ , allow us to price any asset i given payoffs D_i with

$$\mathbf{q} = D_i \cdot \psi = \sum_s \psi_s D_{is}$$

- A one-period riskfree bond with a payoff of 1 in every state has price

$$q_0 = \mathbf{1}'_{S \times 1} \cdot \psi = \sum_s \psi_s$$

- The price of this bond is inverse of the riskfree rate, $q_0 = \frac{1}{R^f}$. Hence

$$R^f = (\mathbf{1}'_{S \times 1} \cdot \psi)^{-1} = \left(\sum_s \psi_s \right)^{-1}.$$

- We can always rewrite the state price vector as

$$\psi = (\mathbf{1}'_{S \times 1} \cdot \psi) \cdot \frac{\psi}{\mathbf{1}'_{S \times 1} \cdot \psi} = \frac{1}{R^f} \cdot \mu,$$

- Observe that

$$\mu = \frac{\psi}{\mathbf{1}'_{S \times 1} \cdot \psi}$$

is a **probability measure** because $1 \geq \mu_i > 0$ for all i and $\sum_i \mu_i = 1$.

- That is, we have an alternative probability distribution over states.
 - We have constructed it by discounting by the risk-free rate.
 - So it is called the **risk-neutral measure**.

- Given our construction, we can always write prices as

$$\mathbf{q} = D \cdot \psi = \frac{1}{R^f} D \cdot \mu.$$

- Since μ is a measure, this is just an **expectation under μ** .
- That is, for some vector $\mathbf{0} \leq \nu \in \mathbb{R}^S$ with $\mathbf{1}'_{S \times 1} \cdot \nu = 1$, we can always write

$$\begin{aligned}\mathbb{E}^\nu[\mathbf{x}] &= \mathbf{x}' \cdot \nu = \sum_s x_s \nu_s \\ \mathbb{E}^\nu[D] &= D \cdot \nu,\end{aligned}$$

for vector \mathbf{x} and $N \times S$ matrix D .

- Hence we can express prices as

$$\mathbf{q} = \frac{1}{R^f} \mathbb{E}^\mu[D].$$

Risk-neutral Measure

- Let \mathbf{p} denote the “physical” (true) probability measure.
- A risk-neutral agent would price assets according to

$$\mathbf{q} = \frac{1}{R^f} \mathbb{E}^{\mathbf{p}} [D].$$

- We have just shown that a risk-averse agent prices assets according to

$$\mathbf{q} = \frac{1}{R^f} \mathbb{E}^{\mu} [D].$$

- μ is the *risk-neutral measure* because risk-averse agents price assets **as if** they were risk-neutral and the probability distribution is μ .
- Risk attitudes are reflected in the tilting of probability.
- Valuable states receive higher probability-weighting under μ than \mathbf{p} .

Martingale Equivalent Measure (MEM)

- Risk-neutral measure is special case of a martingale equivalent measure.
 - Equivalence: $\mu'(s) > 0$ if and only if $p(s) > 0$.
 - Martingale: price process is a martingale under μ' .
- Each MEM is defined with respect to a “numeraire” asset.
- The risk-neutral measure's numeraire is a short-term risk-free asset.
- Another common numeraire is a T -period bond.
- This leads to a T -forward measure.

Definition (Utility Maximization Problem)

An agent has endowment $e \geq 0$ and strictly increasing utility $U : \mathbb{R}_+^s \rightarrow \mathbb{R}$. Dividends and prices of N securities are given by the pair (D, q) . Given portfolio θ , the budget set is

$$B(q, e) = \{e + D'\theta \in \mathbb{R}_+^s : \theta \in \mathbb{R}^N, q \cdot \theta \leq 0\}.$$

The utility maximization problem is:

$$\max_{c \in B(q, e)} U(c) \quad (\text{UMP})$$

Assume there exists a portfolio θ^0 with $D'\theta^0 > 0$. This implies that the wealth constraint on portfolio choices is binding, $q\theta^* = 0$.

Theorem

*If there is a solution to **UMP**, there is no arbitrage. If U is continuous and there is no arbitrage, there is a solution to **UMP**.*

Theorem

Suppose U is strictly concave and differentiable at some $c^ = e + D'\theta^* \gg 0$ with $q \cdot \theta^* = 0$. Then c^* is a solution to **UMP** if and only if $\lambda \partial U(c^*)$ is a state-price vector for a scalar $\lambda > 0$.*

Stochastic Discount Factor (SDF)

- Another way of rewriting our pricing equation is

$$\begin{aligned}\mathbf{q} &= D \cdot \psi = \left(D \cdot \frac{\psi}{\mathbf{p}} \right) \cdot \mathbf{p} = (\pi \cdot D) \cdot \mathbf{p} \\ &= \mathbb{E}^P [\pi \cdot D]\end{aligned}$$

where $\frac{\psi}{\mathbf{p}}$ is interpreted as $\frac{\psi_i}{p_i}$ element-by-element

- We call π a **stochastic discount factor** (or state-price density.)
 - It is a random variable that discounts all payoffs.
 - Another common notation is M , as in $\mathbf{q} = \mathbb{E}^P[M \cdot D]$.
- An SDF prices *all assets*. It all comes down to finding the “right” one.

Stochastic Discount Factor (SDF)

- Recall that asset i 's return is just $R_i^s = \frac{D_{i,s}}{q_i}$. Hence we have

$$1 = \mathbb{E}^P [\pi \cdot \mathbf{R}_i].$$

- For any portfolio ω with $\mathbf{q} \cdot \omega \neq 0$, if $R_\omega^s = \frac{(D' \cdot \omega)_s}{\mathbf{q} \cdot \omega}$, then

$$\mathbb{E}^P [\pi \cdot \mathbf{R}_\omega] = 1.$$

- For any risk-free portfolio with return R_f , we have $1 = \mathbb{E}^P [\pi] R_f$. Hence

$$R_f = \frac{1}{\mathbb{E}^P [\pi]}.$$

Utility Maximization and the SDF: An Example

- Two dates, one of S states realized at date 2. Probability of state s is $p(s)$.
- A full set of Arrow-Debreu securities. Claim on state s has price $q(s)$.
- Initial wealth is W_0 , and $C(s)$ denotes purchases of the s claim.

$$\begin{aligned} \max_{\{C(s)\}_{s=1}^S} \quad & u(C_0) + \sum_{s=1}^S \beta p(s) u(C(s)) \\ \text{s.t} \quad & C_0 + \sum_{s=1}^S q(s) C(s) = W_0. \end{aligned}$$

- First-order condition for any $C(s)$ is

$$\beta p(s) u'(C(s)) = q(s) u'(C_0).$$

Utility Maximization and the SDF: An Example

- D is a diagonal matrix of ones. Hence A-D security prices **are** state prices.
- Rearranging the first-order conditions gives

$$q(s) = \frac{\beta p(s) u'(C(s))}{u'(C_0)}.$$

- Hence the stochastic discount factor is the ratio of marginal utilities:

$$\pi(s) = \frac{q(s)}{p(s)} = \frac{\beta u'(C(s))}{u'(C_0)}.$$

- With CRRA utility, it is a function of consumption growth:

$$\pi(s) = \frac{q(s)}{p(s)} = \beta \left(\frac{C(s)}{C_0} \right)^{-\gamma}$$

- This is the starting point of consumption-based asset pricing.

Uniqueness of State Prices

- If markets are complete, there exists a unique state price vector $\psi \gg 0$.
 - Hence there is a unique SDF and unique MEM.
- If markets are incomplete, there are infinitely many state prices vectors.

Simple argument:

1. Suppose that m^* is an SDF. Then $\mathbf{q} = \mathbb{E}[m^* \cdot D]$.
2. Now pick some $\epsilon \in \mathbb{R}^S$ orthogonal to D , i.e. $\mathbb{E}[\epsilon D] = 0$.
3. Then $m' = m^* + \epsilon$ is also an SDF because

$$\mathbf{q} = \mathbb{E}[(m^* + \epsilon) \cdot D] = \mathbb{E}[m^* \cdot D] + \mathbb{E}[\epsilon \cdot D] = \mathbb{E}[m^* \cdot D].$$

4. Fails in complete markets because there does not exist an orthogonal ϵ .

Some Additional Implications of this Construction

- There *does* exist a unique SDF in the asset span (or payoff space) \mathcal{M} .
- This is because we can always project any SDF onto \mathcal{M} , i.e.

$$m = m^* + \epsilon \quad \text{where} \quad m = \text{proj}(m|\mathcal{M}) \quad \text{and} \quad \mathbb{E}[\epsilon D] = 0.$$

- Easy to verify that m^* is a valid SDF, with identical pricing implications.
 - The projected SDF is sometimes called the “mimicking portfolio” for m .
 - It best summarizes the pricing information in *all* SDFs.
- All differences in SDFs are about **non-marketed payoffs**.
- Another way of saying this: non-traded payoffs may have different prices.

Some Basic Implications

- SDF is a random variable. Use $cov(\pi, D) = \mathbb{E}[\pi \cdot D] - \mathbb{E}(\pi)\mathbb{E}(D)$ to give

$$\begin{aligned}\mathbf{q} &= \mathbb{E}[D]\mathbb{E}[\pi] + cov(\pi, D) \\ &= \frac{\mathbb{E}[D]}{R_f} + cov(\pi, D)\end{aligned}$$

- Prices = risk-neutral discounted value + *risk adjustment*.
- Using the utility maximization example, we have

$$\mathbf{q} = \frac{\mathbb{E}[D]}{R_f} + \frac{cov(\beta u'(C(s)), D(s))}{u'(C_0)}.$$

- *Only assets that co-vary with marginal utility get risk adjustment.*

Some Basic Implications

- We can rewrite the basic equation to reflect returns. For a particular asset,

$$1 = \mathbb{E}[\pi \cdot R_i]$$

- Hence the decomposition is $1 = \mathbb{E}[\pi]\mathbb{E}[R_i] + \text{cov}(\pi, R_i)$. Since $R_f = \mathbb{E}[\pi]^{-1}$,

$$\begin{aligned}\mathbb{E}[R_i] - R_f &= -R_f \text{cov}(\pi, R_i) \\ &= -\frac{\text{cov}(u'(c(s)), R_i)}{\mathbb{E}[u'(c(s))]}.\end{aligned}$$

- This is just saying that excess returns depend only on covariance with π .
- Another way of saying that idiosyncratic risk has no risk premium.

- The expected return equation can be written as

$$\mathbb{E}[R_i] = R_f + \left(\frac{\text{cov}(R_i, \pi)}{\text{var}(\pi)} \right) \left(-\frac{\text{var}(\pi)}{\mathbb{E}[\pi]} \right)$$

or equivalently,

$$\mathbb{E}[R_i] = R_f + \beta_{i,\pi} \lambda_\pi.$$

- The β is the **regression coefficient** of R_i on π .
- The λ is akin to a **price of risk** as determined by the SDF.
- This provides a simple link to empirical analysis.

Multi-factor Structure of SDF

- Assume SDF is a linear combination of K common factors $f_{k,t+1}$, $k = 1, \dots, K$, that are mean-zero and are orthogonal to each other

$$\pi_{t+1} = a_t - \sum_{k=1}^K b_{kt} f_{k,t+1}.$$

- Then it follows that

$$\begin{aligned} -\text{Cov}_t^p \left[\pi_{t+1}, R_{i,t+1} - R_t^f \right] &= \sum_{k=1}^K b_{kt} \sigma_{ikt} = \sum_{k=1}^K \left(b_{kt} \sigma_{kt}^2 \right) \cdot \left(\frac{\sigma_{ikt}}{\sigma_{kt}^2} \right) \\ &= \sum_{k=1}^K \lambda_{kt} \beta_{ikt}. \end{aligned}$$

- sometimes referred to as a "beta-lambda" decomposition in empirical tests
- This form of SDF requires strong assumptions: e.g. static, or M-V utility.

No Arbitrage in Multi-period Models

- We now move to a dynamic setting with $T + 1$ dates, $t = 0, 1, \dots, T$.
- The key difference is that payoffs are now partly endogenous.
- Information is represented by a filtration \mathcal{F} (as defined in Introduction.)
- An adapted process is a sequence $X = \{X_0, \dots, X_T\}$ such that X_t is a random variable with respect $\{\Omega, \mathcal{F}_t\}$ for each t .
- A *security* (or asset) is a claim to an adapted dividend process δ , where δ_t denotes the dividend paid at time t . Each security is associated with an adapted *price process* S , where S_t denotes the ex-dividend price at time t .

No Arbitrage in Multi-period Models

- Assume there are n securities defined by the \mathbf{R}^N -valued dividend process $\delta = (\delta^{(1)}, \dots, \delta^{(N)})$. The associated price process is $S = (S^{(1)}, \dots, S^{(N)})$.
- A *trading strategy* is an adapted process θ in \mathbf{R}^N , where $\theta_t = \{\theta_t^{(1)}, \dots, \theta_t^{(N)}\}$ represents the portfolio (absolute, not in shares) held at time t .
- The dividend process δ^θ generated by a trading strategy is defined by

$$\delta_t^\theta = \underbrace{\theta_{t-1}(S_t + \delta_t)}_{\text{Payoff from previous period}} - \underbrace{\theta_t \cdot S_t}_{\text{Current Expenditures}} .$$

- Trading strategy θ is an **arbitrage** if $\delta^\theta > 0$. (“Something for nothing”).

No Arbitrage in Multi-period Models

- We will use Θ to denote the space of trading strategies.
- For any $\theta, \psi \in \Theta$ and scalars a, b , **assume** $a\delta^\theta + b\delta^\psi = \delta^{a\theta+b\psi}$.
- The marketed subspace (or asset span) $\mathcal{M} = \{\delta^\theta : \theta \in \Theta\}$ is a linear space.

- A **deflator** is any strictly positive adapted process.
- Definition: Deflator π is a **state price deflator** if, for all t ,

$$S_t = \frac{1}{\pi_t} E_t \left(\sum_{j=t+1}^T \pi_j \delta_j \right)$$

- Observation: π is a state-price deflator if and only if

$$\theta_t \cdot S_t = \frac{1}{\pi_t} E_t \left(\sum_{j=t+1}^T \pi_j \delta_j^\theta \right) \quad \text{for all trading strategies } \theta$$

- This is the natural extension of a state-price deflator from the static case.

Theorem (Fundamental Theorem of Finance: Multi-period Version)

The dividend-price pair (δ, S) admits no arbitrage if and only if there is a state-price deflator.

- Proof is similar to the static version using the Riesz Representation Theorem.
- Can be extended to infinite states and time. See Duffie Chapter 2 and 5.

- The gains process for (δ, S) is defined as

$$G_t = S_t + \sum_{j=1}^t \delta_j,$$

which is the history of dividends and the current price

- For any deflator $\gamma \gg 0$, the **deflated gains process** is

$$G_t^\gamma = \gamma_t S_t + \sum_{j=1}^t \gamma_j \delta_j,$$

which is the gains process discounted by γ . (Similar to change in numeraire.)

Theorem

π is a state-price deflator if and only if $S_T = 0$ and G^π is a martingale.

Martingale Equivalent Measure

- As in the static case, we can define equivalent measures to gain insight.
- This requires a numeraire. Assume that there is risk-free short-term asset. If you invest 1 in the risk-free asset at date t , you receive $1 + r_t$ at date $t + 1$ (the *short rate*).
- For any t and $\tau \leq T$, define

$$R_{t,\tau} = (1 + r_t)(1 + r_{t+1}) \cdots (1 + r_{\tau-1}).$$

Definition

An alternative probability measure Q is a martingale equivalent measure if

$$S_t = \mathbb{E}_t^Q \left(\sum_{j=t+1}^T \frac{\delta_j}{R_{t,j}} \right).$$

- This is risk-neutral discounting of dividends under Q .

- We have similar results as before:
 1. There is no arbitrage iff there is a martingale equivalent measure.
 2. Each state-price deflator is associated with a unique MEM.
 3. There is a unique MEM if and only if markets are complete.
- See Duffie Chapter 2 for the full derivation.

- Consider the canonical dynamic utility maximization framework.
- Additively time-separable with strictly concave flow utility u .
- Then no arbitrage implies that the following stochastic Euler equation holds:

$$S_t = \frac{1}{u'_t(c_t^*)} \mathbb{E}_t \left[S_\tau u'_\tau(c_\tau^*) + \sum_{[j=t+1]}^{\tau} \delta_j u'_j(c_j^*) \right] \quad \text{for all } t \text{ and } \tau \geq t.$$

Concrete Implications in a Canonical Framework

- We now study the implications of the general model in a canonical set-up.
- Specifically, an infinite-horizon endowment economy with risky assets.
- An agent has wealth A_t at time t and wants to maximize lifetime utility

$$\mathbb{E}_t \sum_{j=0}^{\infty} \beta^j u(c_{t+j}), \quad 0 < \beta < 1.$$

- (i) \mathbb{E}_t is the expectation given information known at t
- (ii) β is the subjective discount factor
- (iii) c_{t+j} is the agent's consumption in period $t + j$
- (iv) u is concave, strictly increasing, twice continuously differentiable

- There are two assets: a one-period bond and risky equity.
- Bonds earn the risk-free rate R_t . We call L_t the gross payout on the agent's bond holdings between periods t and $t + 1$, with present value $L_t R_t^{-1}$.
 - $L_t < 0$ indicates borrowing. We impose the borrowing constraint $L_t \geq -b_b$.
- An equity position s_t entitles the agent to a risky share of dividends y_t . The ex-dividend price of equity at date t is p_t .
 - $s_t < 0$ indicates a short position, and we impose the constraint $s_t \geq -b_s$.
 - The equity payout y_t is the only source of risk. We can make various assumptions about the driving stochastic process.

- The agent's budget constraint in period t is

$$c_t + R_t^{-1}L_t + p_t s_t \leq A_t.$$

- The evolution of wealth satisfies

$$A_{t+1} = L_t + (p_{t+1} + y_{t+1}s_t).$$

- This is a dynamic programming problem.
 - The state variables are A_t and the history of y .
 - The controls are L_t and s_t .

Intertemporal Euler Equations

- Suppose that the borrowing constraints do not bind.
- First-order conditions associated with L_t and s_t are

$$u'(c_t)R_t^{-1} = \mathbb{E}_t\beta u'(c_{t+1}).$$

$$u'(c_t)p_t = \mathbb{E}_t\beta(y_{t+1} + p_{t+1})u'(c_{t+1}).$$

- These are so-called **Euler equations** pinning down intertemporal optimality.
- They impose joint restrictions on consumption, income, and asset prices.
- Any solution must also satisfy **transversality conditions**:

$$\lim_{k \rightarrow \infty} \mathbb{E}_t \beta^k u'(c_{t+k}) R_{t+k}^{-1} L_{t+k} = 0.$$

$$\lim_{k \rightarrow \infty} \mathbb{E}_t \beta^k u'(c_{t+k}) p_{t+k} s_{t+k} = 0.$$

A Famous Question: Are Prices Martingales?

- An intuitive definition of *market efficiency* is that prices are martingales: all information is incorporated today, so we can't "predict" price movements.
- The Euler equation for equity shows that this will generically fail. We write

$$p_t = \mathbb{E}_t \beta (y_{t+1} + p_{t+1}) \frac{u'(c_{t+1})}{u'(c_t)}$$

- Using the covariance formula $\mathbb{E}xy = \mathbb{E}x\mathbb{E}y + \text{cov}(x, y)$ implies that

$$p_t = \beta \mathbb{E}_t (y_{t+1} + p_{t+1}) \mathbb{E}_t \frac{u'(c_{t+1})}{u'(c_t)} + \beta \text{cov}_t \left[(y_{t+1} + p_{t+1}), \frac{u'(c_{t+1})}{u'(c_t)} \right].$$

- For prices to be a martingale, we require $\mathbb{E}_t \frac{u'(c_{t+1})}{u'(c_t)} = \text{const}$ and $\text{cov}[\cdot] = 0$.
- Both restrictions require very strong assumptions.

A Famous Special Case: Risk Neutrality

- Suppose now that agents are risk neutral so that $u'(c_t) = \text{const.}$ Then

$$p_t = \beta \mathbb{E}_t(y_{t+1} + p_{t+1})$$

- This has the general class of solutions

$$p_t = \mathbb{E}_t \sum_{j=1}^{\infty} \beta^j y_{t+j} + \xi_t \left(\frac{1}{\beta} \right)^t.$$

where ξ_t is any random process that satisfies $\mathbb{E}_t \xi_{t+1} = \xi_t$ (a martingale).

- This is the discounted sum of expected dividends plus a “bubble term.”
 - The bubble term is typically zero in general equilibrium.

- Denote the state of the economy by s_t and assume that it follows a Markov process with transition probabilities $\mu(s_{t+1}|s_t)$.
- Assume that an asset pays a dividend stream $\{d(s_t)\}_{t \geq 0}$.
- Using the Euler equation, the cum-dividend price follows the recursion

$$a(s_t) = d(s_t) + \beta \sum_{s_{t+1}} \mu(s_{t+1}|s_t) \frac{u'_{t+1}[c(s_{t+1})]}{u'_t[c(s_t)]} a(s_{t+1}).$$

Constructing the Risk-Neutral Measure

- We can rewrite this equation as

$$a(s_t) = d(s_t) + R_t^{-1} \sum_{s_{t+1}} \tilde{\mu}(s_{t+1}|s_t) a(s_{t+1}) = d(s_t) + R_t^{-1} \tilde{\mathbb{E}}_t a(s_{t+1}).$$

- To do so, we define the risk-free rate as the inverse sum of state prices,

$$R_t^{-1} = \beta \sum_{s_{t+1}} \mu(s_{t+1}|s_t) \frac{u'_{t+1}[c(s_{t+1})]}{u'_t[c(s_t)]}$$

and the risk-neutral **transition measure** as

$$\tilde{\mu}(s_{t+1}|s_t) = R_t \beta \frac{u'_{t+1}[c(s_{t+1})]}{u'_t[c(s_t)]} \mu(s_{t+1}|s_t)$$

where multiplying by R_t ensures that the “twisted” measure is in $(0, 1)$.

- We can then construct an “overall” risk-neutral measure using

Verifying the Martingale Part

- Consider an asset that pays $d_T = d(s_T)$ at date T and 0 otherwise.
- Prices satisfy $a_T(s_T) = d(s_T)$ and

$$a_t(s_t) = \mathbb{E}_{s_t} \beta^{T-t} \left[\frac{u'(c_T(s_T))}{u'(c_t(s_t))} \right] a_T(s_T).$$

- Now consider some $t < T$ and define the deflated process

$$\tilde{a}_{t+j} = \frac{a_{t+j}}{R_t R_{t+1} \cdots R_{t+j-1}} \quad \text{for } j = 1 \dots T-1.$$

- Then we can verify that $\tilde{\mathbb{E}}_t \tilde{a}_{t+j} = \tilde{a}_t(s_t)$ where $\tilde{a}_t(s_t) = a(s_t) - d(s_t)$.

- An equivalent statement of the same result is that

$$\tilde{\mathbb{E}}[a(s_{t+1}|s_t)] = R_t[a(s_t) - d(s_t)].$$

Adjusting for interest rates and dividends, the asset prices is a martingale **with respect to the risk-neutral measure!**

Asset Prices in (General) Equilibrium

- Where does the consumption process and the risk-free rate come from?
- To do so, we need to specify a production possibility frontier.
- We now specialize our economy to the Lucas (1978) economy.
- There is a large number of identical agents. The only durable good in the economy is set of identical “trees,” one for each person in the economy.
- At the beginning of period t , each tree yields a dividend of “fruit” y_t . The fruit is not storable, but the tree is perfectly durable. The **state** is $s_t = y_t$.
- There is a time-invariant transition p.d.f $Prob(s_{t+1} \leq s' | s_t = s) = F(s', s)$.
- Number of shares in a tree is normalized to 1. Bonds are in zero net supply.

Asset Prices in (General) Equilibrium

- Since all agents are identical, we consider a single “representative agent.”
(More on when and why we can do this later).
- Since this an endowment economy, the market clearing condition is $c_t = y_t$.
(This is **indifference pricing**: no trade on the equilibrium path).
- Using this restriction yields the following Euler equations:

$$u'(y_t)R_t^{-1} = \mathbb{E}_t\beta u'(y_{t+1}).$$

$$u'(y_t)p_t = \mathbb{E}_t\beta(y_{t+1} + p_{t+1})u'(y_{t+1}).$$

- Now use the law of iterated expectations $\mathbb{E}_t\mathbb{E}_{t+1}(\cdot) = \mathbb{E}_t(\cdot)$ and iterate:

$$u'(y_t)p_t = \mathbb{E}_t \sum_{j=1}^{\infty} \beta^j u'(y_{t+j})y_{t+j} + \mathbb{E}_t \lim_{k \rightarrow \infty} \beta^k u'(y_{t+k})p_{t+k}.$$

Asset Prices in (General) Equilibrium

- The limiting term on RHS must be zero (Why?). Hence the asset price is

$$p_t = \mathbb{E}_t \sum_{j=1}^{\infty} \beta^j \frac{u'(y_{t+j})}{u'(y_t)} y_{t+j}.$$

- This a nice generalization of our previous risk-neutral discounting formula.
- Risk aversion and aggregate risk \Rightarrow time-varying stochastic discount rates.
- Under a Markov transition matrix, we also know that $p_t = p(s_t)$.

- A simple example with a particular clean solution is log utility.
- If $u(c) = \log(c)$ then $u'(c) = c^{-1}$. Hence our solution becomes

$$p_t = \mathbb{E}_t \sum_{j=1}^{\infty} \beta^j y_t = \frac{\beta}{1 - \beta} y_t.$$

What does this say about price cyclicalty and sensitivity to shocks?

Risk-Sharing and The Existence of Representative Agents

- Consider a complete-markets model with different agents indexed by i .
- Assume that these agents agree on the probability distribution over states.
- The first-order condition for any Arrow-Debreu claim on state s_{t+1} is

$$\beta\mu(s_{t+1}|s_t)u'_i(c_{t+1}^i(s_{t+1})) = q(s_{t+1}|s_t)u'_i(c_t^i(s_t)).$$

- We can rearrange this to solve for the claims price:

$$\beta\mu(s_{t+1}|s_t)\frac{u'_i(c_{t+1}^i(s_{t+1}))}{u'_i(c_t^i(s_t))} = q(s_{t+1}|s_t)$$

We can also take ratios of two states, s_{t+1} and s'_{t+1} , to give

$$\frac{\mu(s_{t+1}|s_t)u'_i(c_{t+1}^i(s_{t+1}))}{\mu(s'_{t+1}|s_t)u'_i(c_{t+1}^i(s'_{t+1}))} = \frac{q(s_{t+1}|s_t)}{q(s'_{t+1}|s_t)}$$

- The right-hand side of these equations is the same for all agents!
- Leads to perfect risk-sharing: marginal utilities are aligned state-by-state.
- Moreover, agents have the same ordering of marginal utility across states.
- We can construct a utility function that represents this ordering. This is the utility function of the representative agent. It need not be related directly to underlying agent preferences.
- This argument works only in complete markets. (Why?)

Another Convenient Feature of Complete Markets

- We can appeal to Welfare Theorems: market allocation is Pareto efficient.
- Hence we can solve a Social Planner's problem to obtain allocations.
- Social Planner's problem (appeal to First Welfare Theorem)

$$\max_{\{c_t^i, c_t^j\}} \eta_i \mathbb{E} \left[\sum_t \beta^t u_i (C_t^i) \right] + \eta_j \mathbb{E} \left[\sum_t \beta^t u_j (C_t^j) \right], \text{ s.t. } c_t^i + c_t^j = C_t,$$

with Pareto weights η_i and η_j , and FOC

$$\eta_i u_i' (C_t^i) = \eta_j u_j' (C_t^j).$$

- Condition reflects perfect risk-sharing, and holds ex-ante and ex-post.

- No Arbitrage and the Stochastic Discount Factor
- **Bounds on SDFs as a Diagnostic Tool**
- Applications of SDF and Risk-neutral Measures

- Recall that we have the basic asset pricing equation $1 = \mathbb{E}[m \cdot R_i]$.
- We showed that this can be decomposed as

$$1 = \mathbb{E}[m]\mathbb{E}[R_i] + \text{cov}(m, R_i) = \mathbb{E}[m]\mathbb{E}[R_i] + \rho_{m,R_i}\sigma(R_i)\sigma(m).$$

This implies the following, where $\rho'_{m,R_i} \in [-1, 1]$:

$$\mathbb{E}R_i = R_f - \rho_{m,R_i}\sigma(R_i)\frac{\sigma(m)}{\mathbb{E}m}.$$

Hence we can bound the volatility of the stochastic discount factor:

$$\frac{\sigma(m)}{\mathbb{E}m} \geq \frac{|\mathbb{E}[R_i^e]|}{\sigma(R_e)}.$$

Hansen-Jagannathan Bounds

- The right-hand side is the Sharpe Ratio of asset i .
- Hence we have a lower bounds on the volatility of the SDF.
- This bound is particularly tight if we know the risk-free rate $R_f = 1/\mathbb{E}m \approx 1$.
- It is also tightest for the asset with the highest Sharpe Ratio.

- We can find the tightest bound using mean-variance analysis.
- This produces a set of SDFs (also defined by mean-variance) that can price a given set of assets.
This is a very useful tool for diagnosing the potential of a model.

- We will discuss this further. HJ provide full analysis without risk-free asset.

- Alvarez and Jermann (2005) use entropy bounds to define a lower bound on the volatility of the “permanent component” of an SDF.
- That is, they decompose $M_t = M_t^P M_t^T$ where M_t^P is a martingale.
- This allows us to get information about the SDF from long-dated assets.
- Define entropy of a positive random variable X as

$$L(X) = \log E[X] - E[\log X] \geq 0.$$

- for lognormal random variables, $L(X) = \frac{1}{2}\sigma_x^2$ ($x = \log X$)
- $L(aX) = L(X)$ for constant a

- In a finite-state model, we have

$$\pi = \frac{\psi}{\mathbf{p}} = \frac{1}{R^f} \cdot \frac{\mu}{\mathbf{p}},$$

where again μ is risk-neutral measure

- It then follows if R^f is constant (returns i.i.d. in a dynamic setting) that

$$\begin{aligned} L(\pi) &= L\left(\frac{1}{R^f} \frac{\mu}{\mathbf{p}}\right) = L\left(\frac{\mu}{\mathbf{p}}\right) \\ &= \log E^P \left[\frac{\mu}{\mathbf{p}} \right] - E^P \left[\log \left(\frac{\mu}{\mathbf{p}} \right) \right] = -E^P \left[\log \left(\frac{\mu}{\mathbf{p}} \right) \right]. \end{aligned}$$

- Entropy of SDF is a measure of deviation of μ from \mathbf{p} . AJ (2005) show that

$$L(\pi) \geq E \left[r_j - r^f \right].$$

- a high log risk premium implies high entropy of SDF.

- Proof: Since $E^P[\pi \cdot \mathbf{R}_i] = 1$, $E^P[\log \pi] + E^P[\log \mathbf{R}_i] \leq \log E^P[\pi \cdot \mathbf{R}_i] = 0$, from which follows that

$$E^P[\log \mathbf{R}_i] \leq -E^P[\log \pi].$$

- Allowing for time-variation in price of riskless asset: $1/R_t^f = E_t^P[\pi_{t+1}]$, entropy of riskless asset price is

$$L\left(R_t^{f-1}\right) = \log E_t^P\left[R_t^{f-1}\right] - E_t^P\left[\log R_t^{f-1}\right] = \log E_t^P[\pi] + E_t^P\left[\log R_t^f\right].$$

- It then follows from these two results that

$$\begin{aligned} L(\pi) &= \log E^P[\pi] - E^P[\log(\pi)] \\ &\geq L\left(R_t^{f-1}\right) + E^P\left[\log \mathbf{R}_i - \log R^f\right] \\ &\geq E^P\left[\log \mathbf{R}_i - \log R^f\right]. \end{aligned}$$

- Ultimately, Alvarez-Jermann provide a lower bound on the volatility of the permanent component of M_t relative to the overall volatility of M_t .
- The empirical implementation argues that prices of long-dated bonds reflect properties of the permanent component.
- To be consistent with the pricing of long-dated bounds, models must therefore have volatile *permanent* innovations to the SDF.

- No Arbitrage and the Stochastic Discount Factor
- Bounds on SDFs as a Diagnostic Tool
- **Applications of SDF and Risk-neutral Measures**

Physical vs Risk-neutral Measures

- Suppose we know the risk-neutral probabilities of a state. What good is this without knowing the true state prices?
- Black-Scholes show we can make progress on pricing redundant assets.
- The prototypical example is an option, which can be replicated using a stock and a bond.
- More generally, we can decompose state prices into

$$\psi_t = \pi_t p_t,$$

which compose the risk-neutral measure through $\mu_{st+1} = \frac{\psi_{st+1}}{\sum_{s=1}^S \psi_{st+1}}$

- If we can observe μ_{st+1} , can we learn anything about π_t and p_t ?

Physical vs Risk-neutral Measures

- In principle, one can recover μ_{t+1} from observing a cross-section of option prices that differ in their strike price K (Breen and Litzenberger (1978)).
- For a call option for date T with price $C_0(K)$ for strike price K on underlying stock with price S_t , one has that

$$C_0(K) = E^Q \left[\frac{1}{R_{0,T}} (S_T - K) \cdot 1_{\{S_T \geq K\}} \right],$$

from which follows

$$\frac{\partial^2 C_0(K)}{\partial K^2} = \frac{\partial}{\partial K} \left(\frac{1}{R_{0,T}} (S_{sT} - K) \mu_{sT} \right) = -\frac{1}{R_{0,T}} \mu_{sT}.$$

(Here we are abstracting from issues of liquidity).

- We cannot decompose μ_{sT} , into π_t and p_t without more structure. High state price can reflect high marginal utility or high likelihood of the state

- With complete markets, FOC for representative agent is

$$U'_i \psi_{ij} = \beta U'_j p_{ij},$$

where ψ_{ij} is the Arrow-Debreu state price for state j if current state is i , and we can interpret $U'_i = U'_i(c(\theta_i))$

- We can write this as SDF $\Lambda_{1,j} = \beta \frac{U'_j}{U'_1}$, letting the current state be 1.

- Stacking $\psi_t = \pi_t p_t$ into matrix form, one has the matrix equation

$$G\Psi = \beta PG,$$

where Ψ is the $S \times S$ matrix of state contingent Arrow-Debreu prices ψ_{ij} , P is the $S \times S$ matrix of natural probabilities p_{ij} , and G is the diagonal matrix with the undiscounted kernel

$$G = \frac{1}{U'_1} \begin{bmatrix} U'_1 & 0 & 0 \\ 0 & U'_i & 0 \\ 0 & 0 & U'_m \end{bmatrix},$$

and no arbitrage is guaranteed with strictly positive state prices

Ross Recovery Theorem (Ross (2015))

- Manipulating the matrix equation

$$P = \frac{1}{\beta} G \Psi G^{-1}.$$

We have S^2 equations with S^2 unknown probabilities, S unknown marginal utilities, and 1 discount rate

- Ross (2015) has insight that, since P is a stochastic matrix whose rows are transition probabilities, one also has the additional restriction

$$P \cdot \mathbf{1}_{S \times 1} = \mathbf{1}_{S \times 1}.$$

- He uses this to back out the physical measure. (Details in paper).
- Borovicka, Hansen, and Scheinkman (2016) argue Ross (2015) is able to recover p_t only using restrictions on the SDF that are easily rejected.

- Suppose nominal price of an asset is $P_t q_{it}$ that pays dividend $P_t \delta_{it}$, where P_t is the price level and q_{it} is the price in the numeraire.
- Then no arbitrage pricing requires

$$\hat{\pi}_t P_t q_{it} = E_t^P [\hat{\pi}_{t+1} P_{t+1} (\delta_{it+1} + q_{it+1})],$$

which can be rewritten, with $i_{t+1} = \frac{P_{t+1}}{P_t}$ as inflation, as

$$q_{it} = E_t^P \left[\frac{\hat{\pi}_{t+1}}{\hat{\pi}_t} i_{t+1} (\delta_{it+1} + q_{it+1}) \right] = E_t^P \left[\frac{\pi_{t+1}}{\pi_t} (\delta_{it+1} + q_{it+1}) \right],$$

where second equality is from definition of pricing real assets

- It then follows the above holds state-by-state, and the nominal SDF $\hat{\Lambda}_{t,t+1} = \frac{\hat{\pi}_{t+1}}{\hat{\pi}_t}$ and the real SDF $\Lambda_{t,t+1}$ are related by

$$\Lambda_{t,t+1} = \hat{\Lambda}_{t,t+1} i_{t+1}.$$